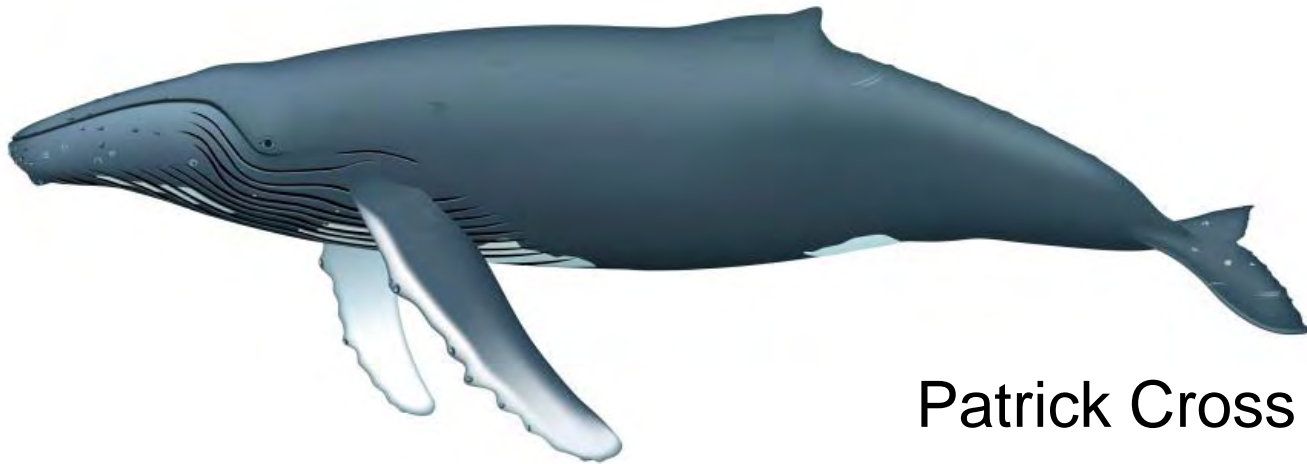
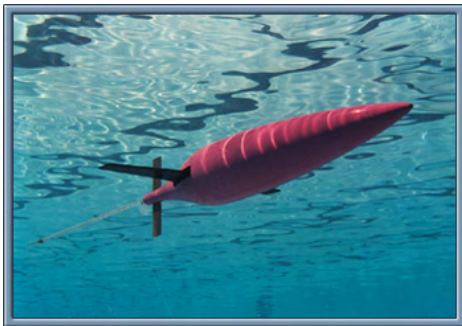
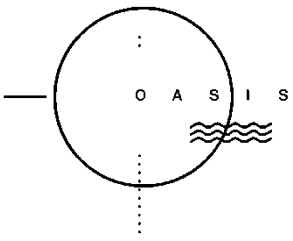


# Using Ocean Gliders for Passive Acoustic Monitoring of Marine Mammals



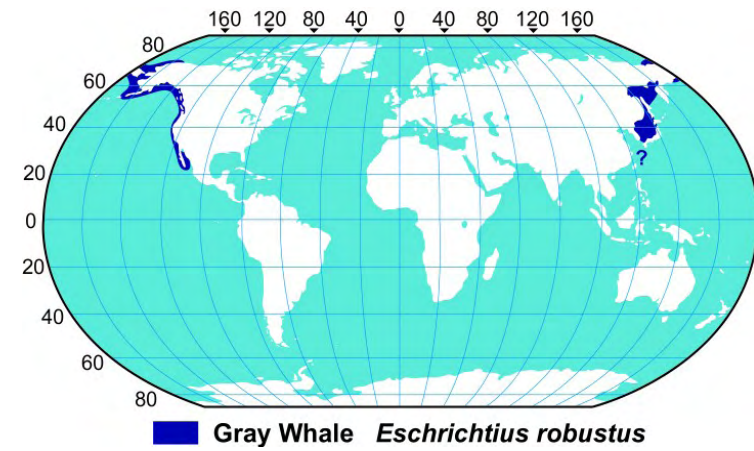
Patrick Cross  
Senior Scientist, OASIS, Inc.  
Sponsored by CEROS and ONR

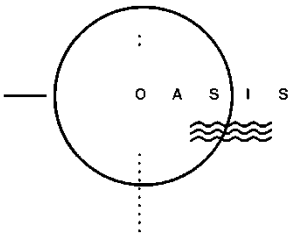




# Motivation

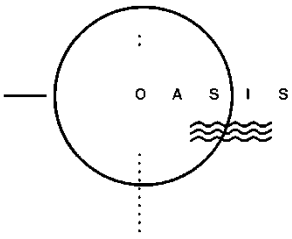
- Mammal monitoring relevant to:
  - Conduct of Navy exercises
  - Avoiding vessel/mammal collisions (Superferry, etc.)
  - MM distribution, migration
  - Relating MM presence/activity to oceanography, anthropogenic influences





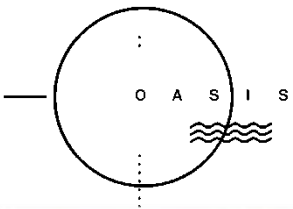
# Acoustic Monitoring

- Most mammals vocalize with some form of exploitable calls – songs, clicks, whistles
- Acoustic monitoring augments visual observation
  - Day/night
  - All weather/visibility
- Acoustic monitoring should be viewed as an essential component to a comprehensive marine mammal monitoring solution

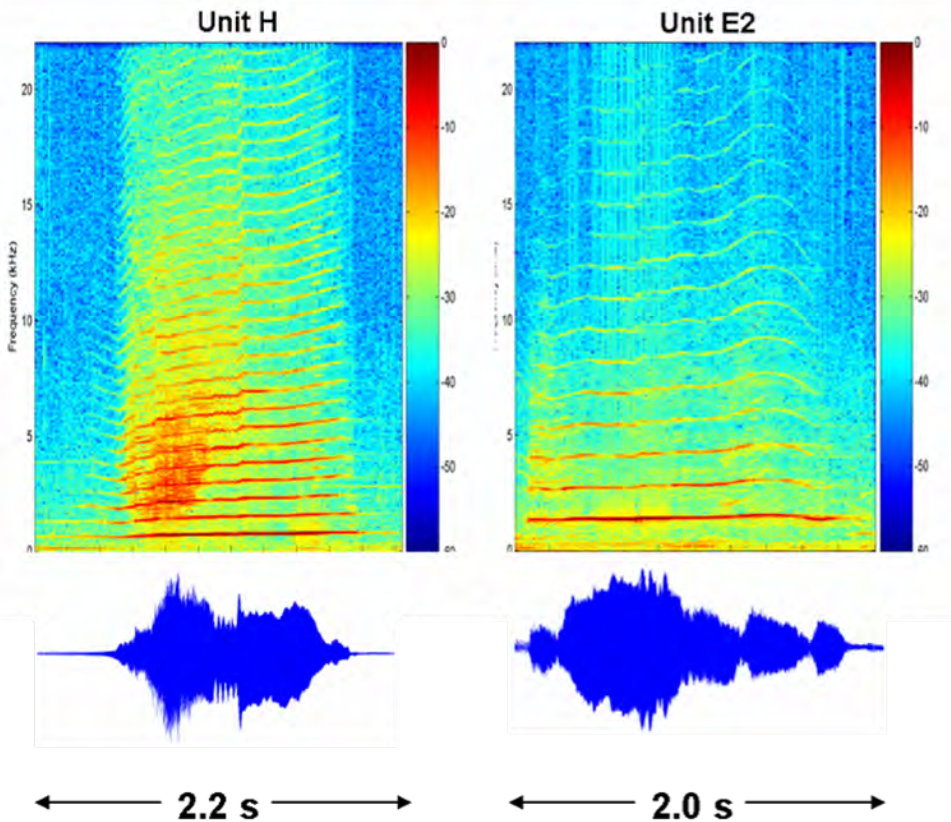


# Challenge

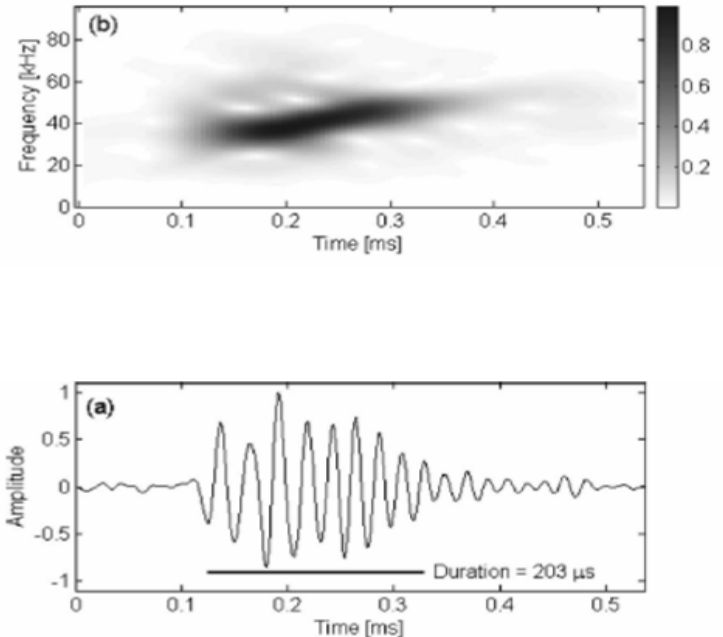
- Vocalizations are extremely varied in character
  - Blue whales – very low frequency (~20 Hz), long range detections
  - Humpback whales – many varied song components, wide frequency range (~100 Hz – several kHz)
  - Minke whales – distinctive “boing” and “star wars” sounds
  - Dolphins – very high frequency whistles and foraging clicks, some exceeding 100 kHz
  - Beaked whales – high frequency (10’s of kHz), very directed and narrow in beam width, vocalizations only when foraging deep (to > 1200m)
- Not much acoustic data available on some species
- Some features of OASIS monitoring approach
  - Autonomous detection and reporting of marine mammal vocalizations
  - Classification of species
  - Broad area coverage (multiple systems)
  - Persistent
  - Relocatable



# Variety of Whale Sounds



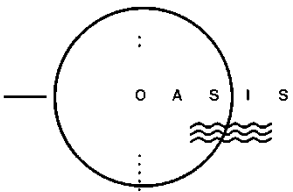
Spectrograms of Humpback whale song units in Hawaii. From Au et al, 2006.



Cuvier's Beaked whale clicks: a) time series, b) spectrogram. From Tyack et al., 2006.

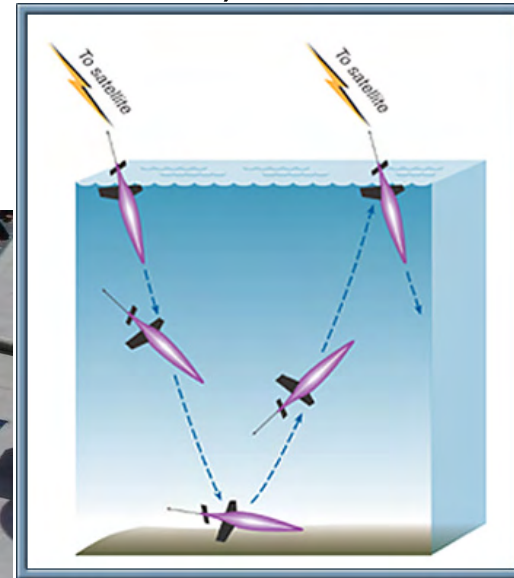
Key is to design classification algorithms that can reside in onboard signal processors and recognize these signals when received, allowing transmission of detection messages when glider surfaces.

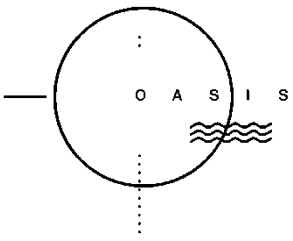




# Gliders

- No motorized propulsion (quiet)
- Driven by buoyancy changes
- Wings add horizontal component to motion
- About 6 ft, 120 lbs
- CTDs for long-term ocean monitoring
- Host various other sensors (optical, biological, chemical, etc.)
- Persist at sea for weeks/months
- Compared to ships, very cheap!





# Seaglider

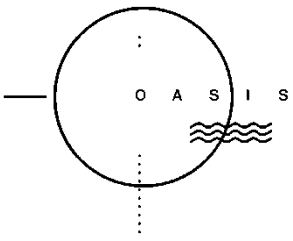
## University of Washington



|                |                                  |
|----------------|----------------------------------|
| Displacement   | 52 liters                        |
| Dimensions     | 1.8 m long<br>30 cm max diameter |
| Batteries      | Lithium Primary                  |
| Communications | Iridium                          |
| Speed          | ~ 0.25 m/s                       |
| Endurance      | 6 months or more                 |
| Depth Range    | ~ 50 m to 1000 m                 |

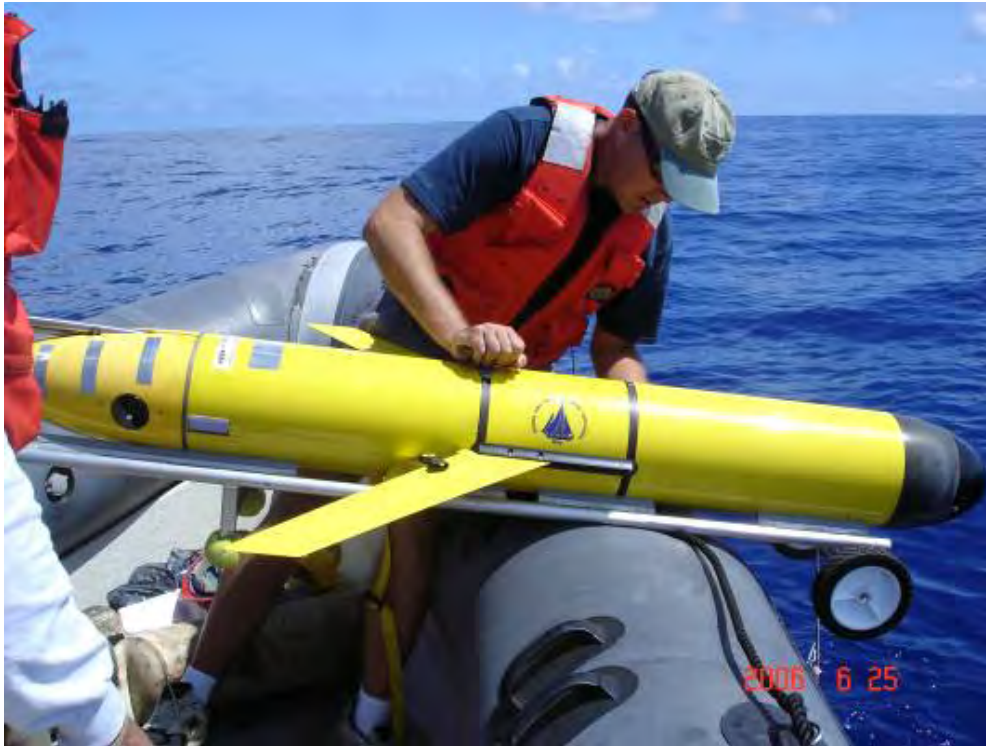


- Buoyancy controlled by inflation/deflation of oil bladder
- Pitch and roll controllable through movement of battery packs
- No rudder
- Communications/GPS in 1m tail/antenna



# Slocum Glider

Webb Research, Inc.



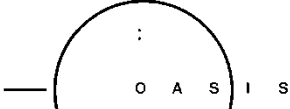
|                |                              |
|----------------|------------------------------|
| Displacement   | 52 liters                    |
| Dimensions     | 1.8 m long<br>21 cm diameter |
| Batteries      | Alkaline                     |
| Communications | Iridium or RF                |
| Speed          | ~ 0.25 m/s                   |
| Endurance      | 28 to 50 days                |
| Depth Range    | 4 to 200 m                   |



- Buoyancy controlled by movement of water in/out of glider's nose
- Pitch controllable through movement of battery packs
- Has rudder for greater navigability in shallow water
- Communications/GPS in tail/antenna



# Ocean Gliders – RIMPAC 06



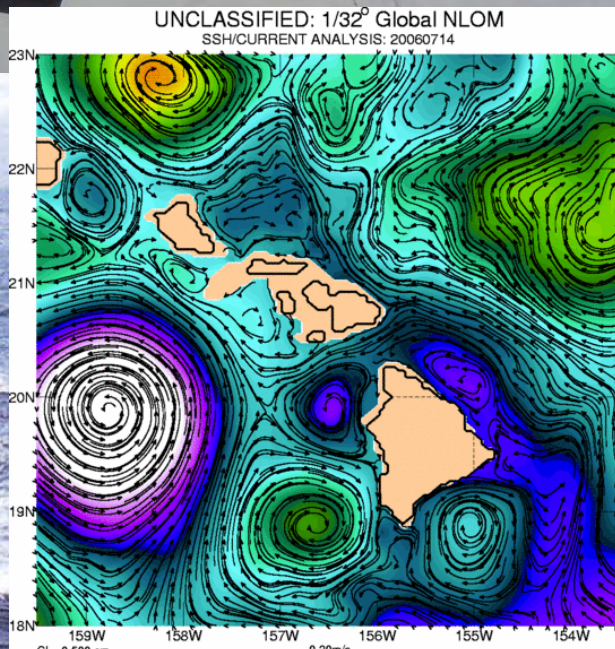
- 6 gliders in support of ASW
  - 4 Seagliders (1000m)
  - 2 Slocum gliders (200m)
- Deployed 25 June – 29 July
- ONR – Sponsor, provided gliders
  - APL-UW, UHawaii, SPAWAR, OASIS, NAVOCEANO

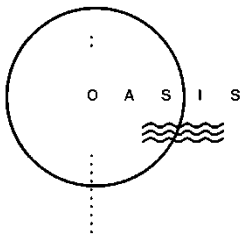
## Challenges

- Deconflicting with foreign subs
- Strong currents
- Loss of 1 Slocum

## So What

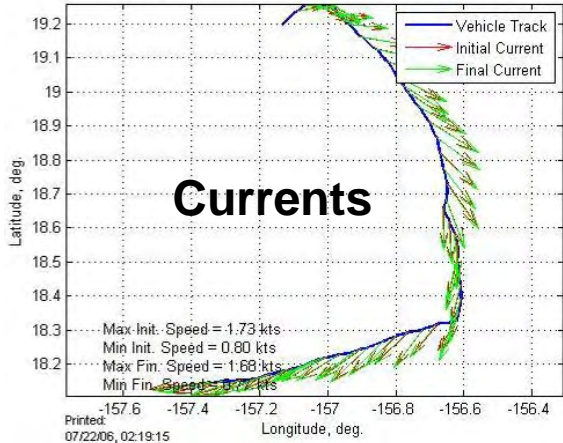
- Improvement in eddy characterization
- Cost savings (versus P-3/ship)





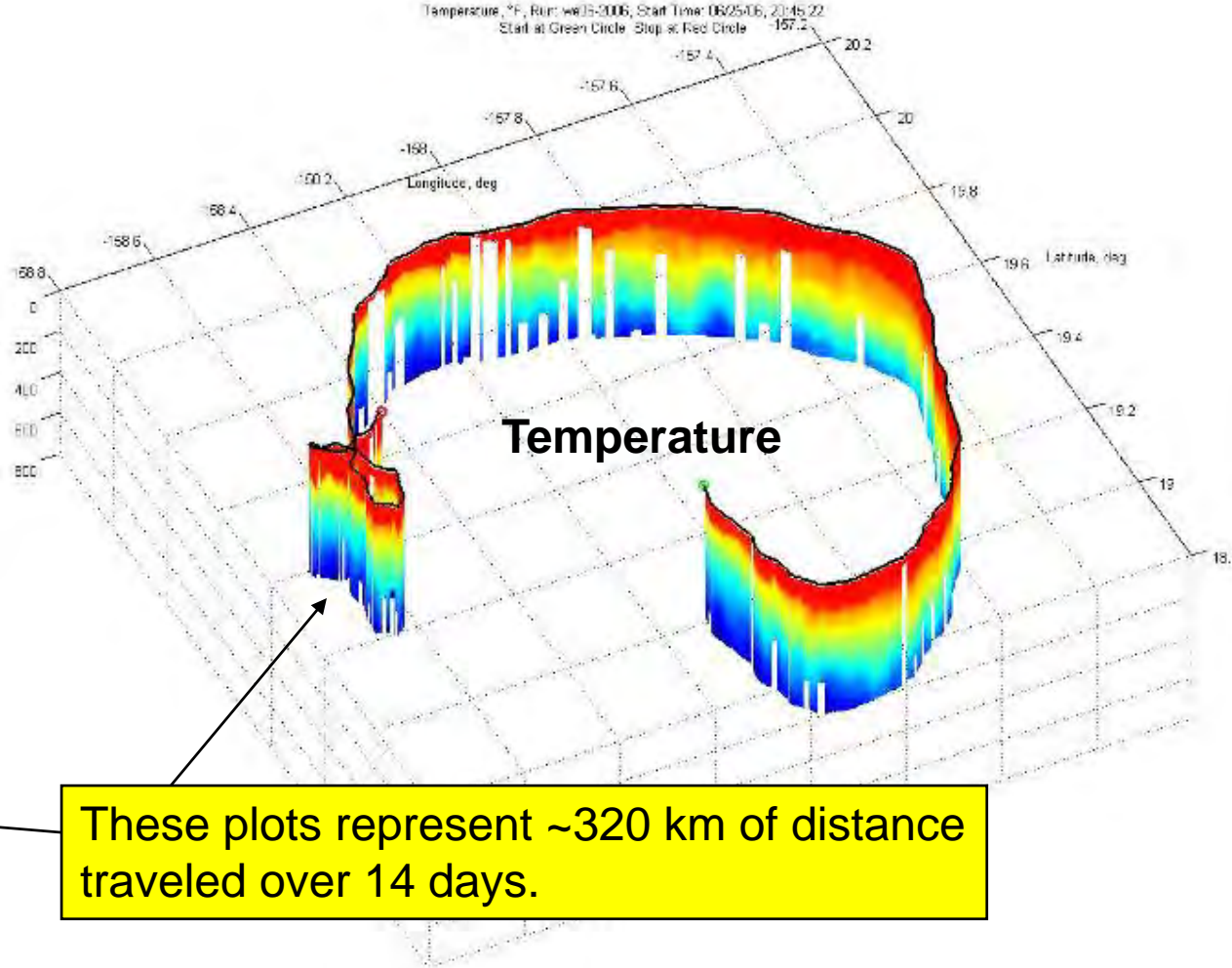
# RIMPAC 06 Glider Data

Surf. Current Vector Plot, Run: we06-2006, Start Time: 07/16/06, 04:45:14



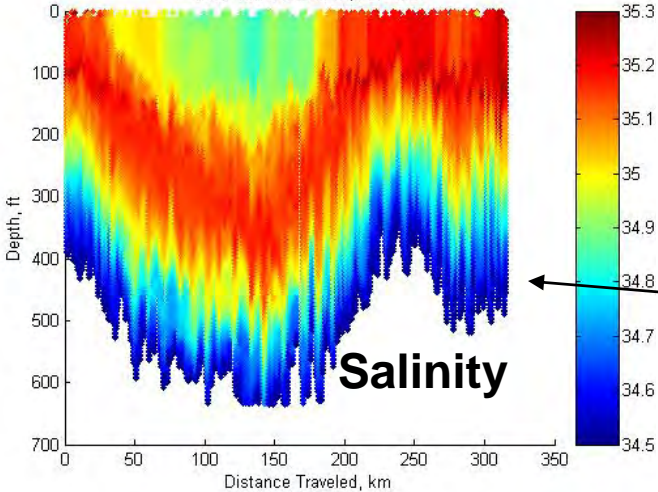
**Currents**

Temperature, °F, Run: we06-2006, Start Time: 06/25/06, 20:45:22  
Start at Green Circle Stop at Red Circle



**Temperature**

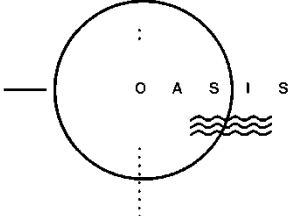
Salinity Cross-section, psu, Run: we06-2006  
Start Time: 06/25/06, 20:45:22



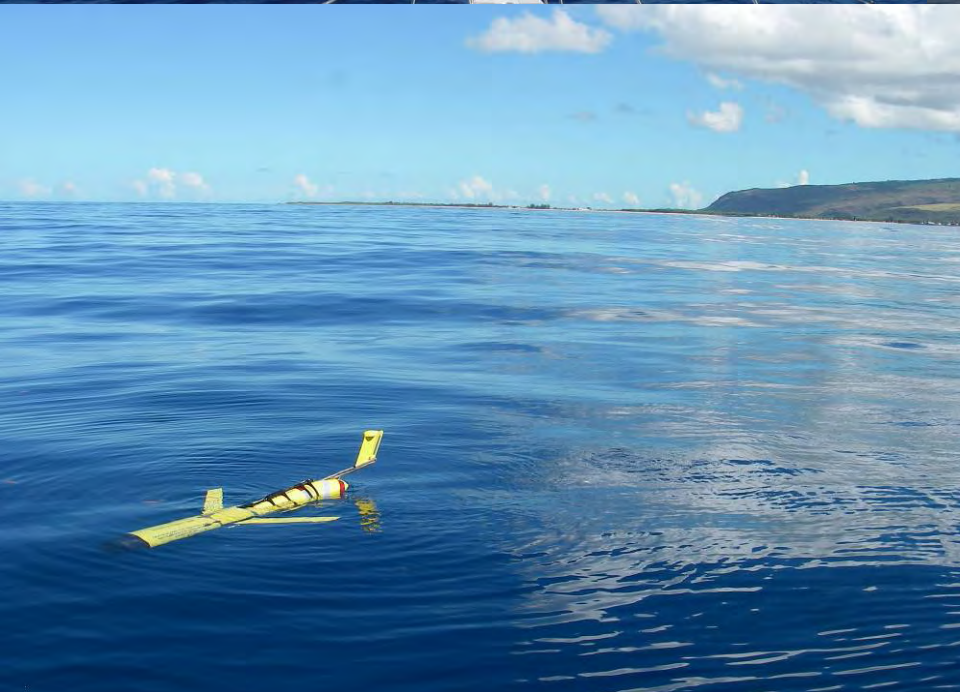
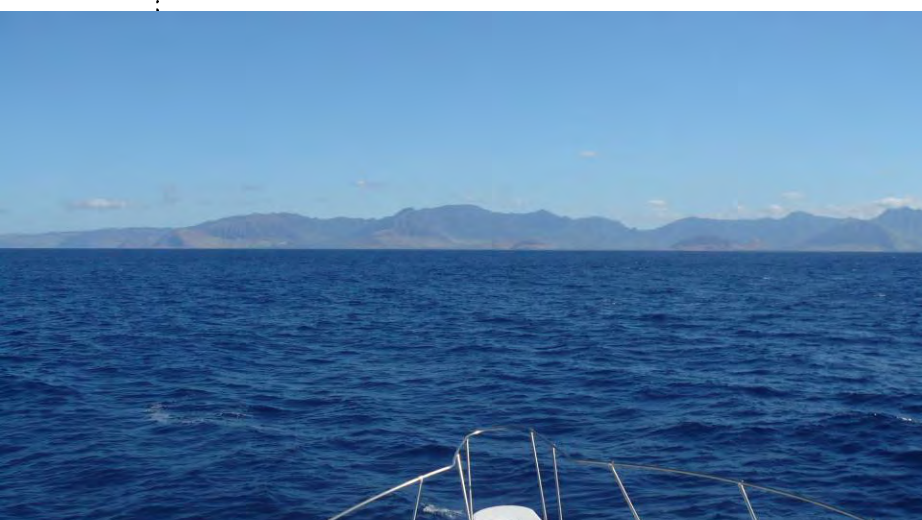
**Salinity**

These plots represent ~320 km of distance traveled over 14 days.





# Recent Tests in Hawaii





# 2008 Hawaii Tests

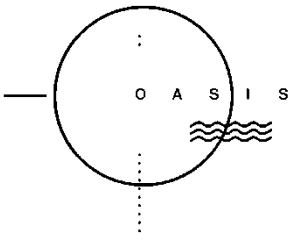


The image is a bathymetric map of the Hawaiian Islands, showing depth contours and color-coded elevations. The map is oriented with the Hawaiian Islands running from the top-left to the bottom-right. The colors range from red (shallow) to blue (deep). Two specific areas are highlighted with black circles and arrows pointing to text boxes. The first box, on the left side of the map, points to a shallow area near the main Hawaiian Islands. The second box, on the right side, points to a shallow area near the southern part of the Hawaiian Islands.

HF Summer Tests  
(Beaked Whales,  
dolphins)

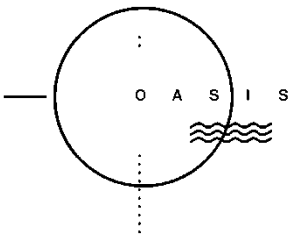
LF Winter Tests  
(Humpback Whales)



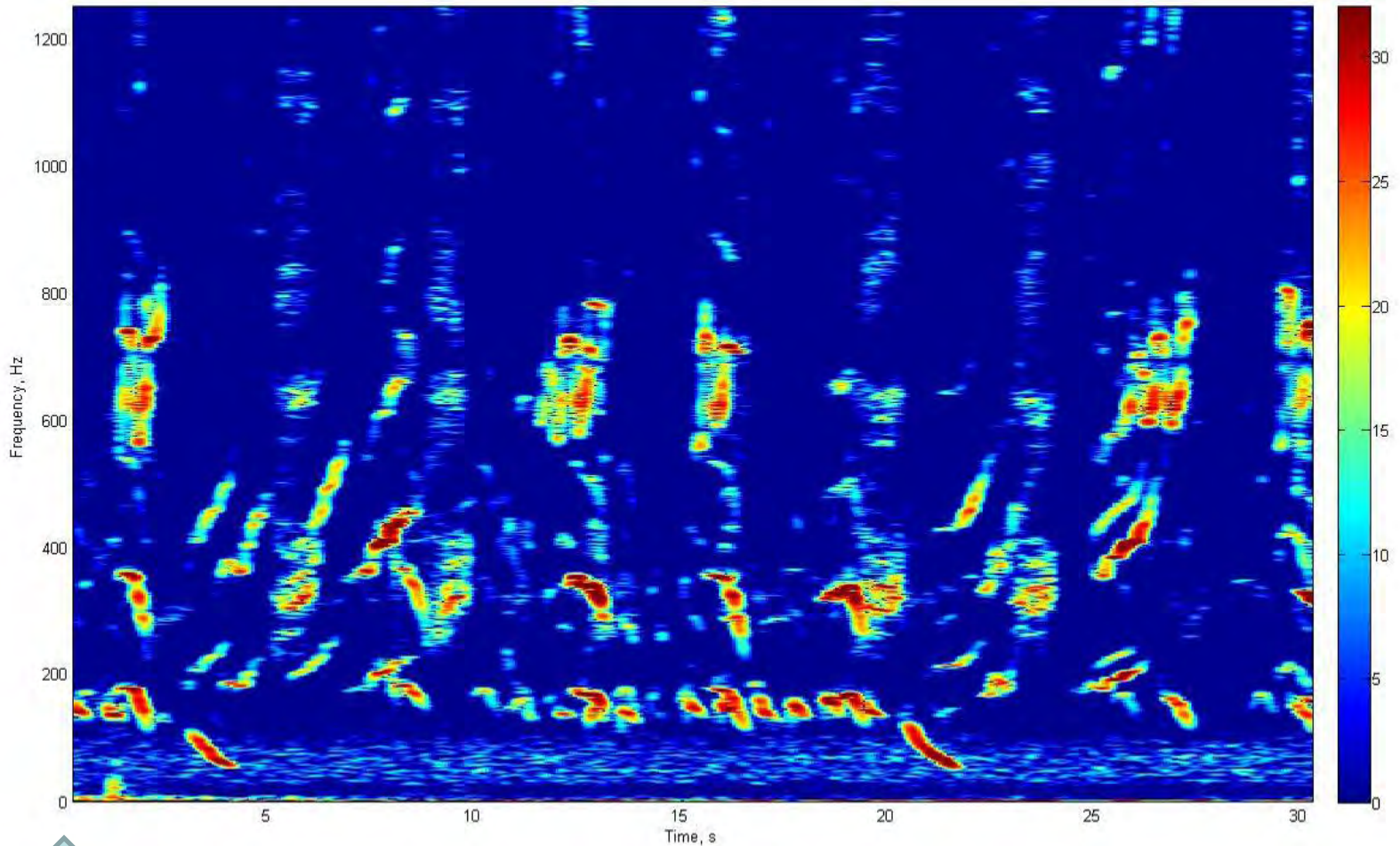


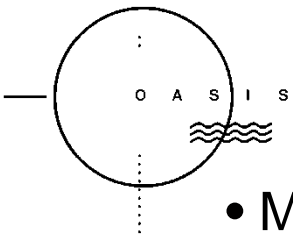
# Hawaii Tests

- Low-frequency (<100 Hz to 1 kHz)
  - February 2008
  - Focused on humpback whales, off leeward Oahu
  - Recorded abundant humpback songs onboard glider
  - Coordinated with HIMB singer localization
  - Autonomous reporting of mammal detections
- High-frequency (tens of kHz)
  - July/August 2008
  - Focused on beaked whales, off leeward Kauai
  - Recorded 94 hours of HF data



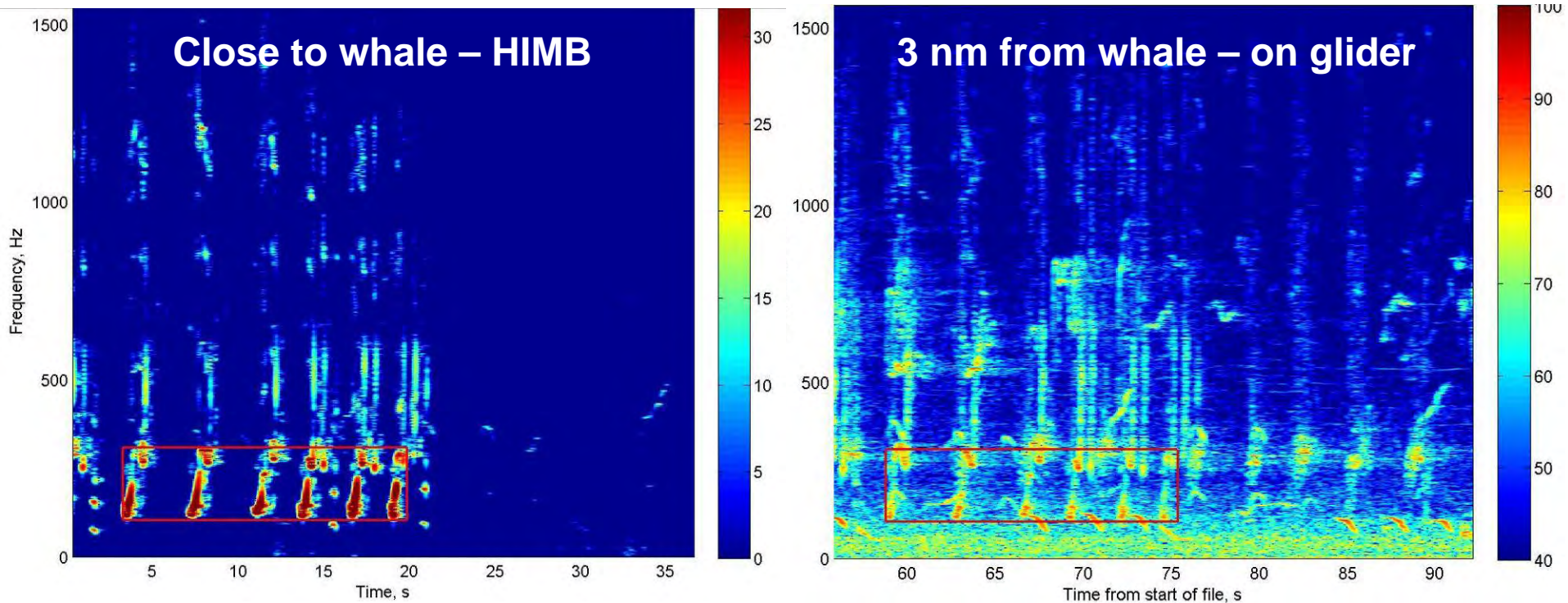
# LF (Humpback) Signals Detected



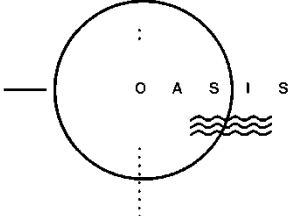


# Role of HIMB

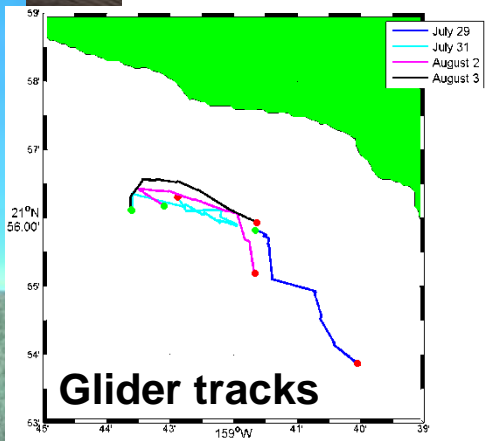
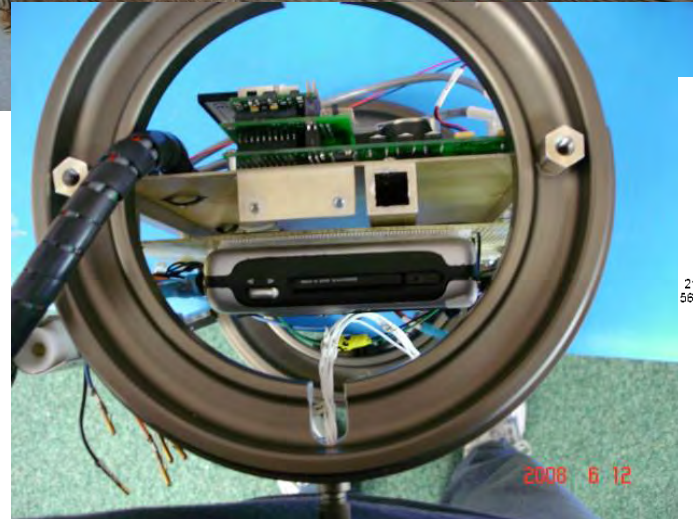
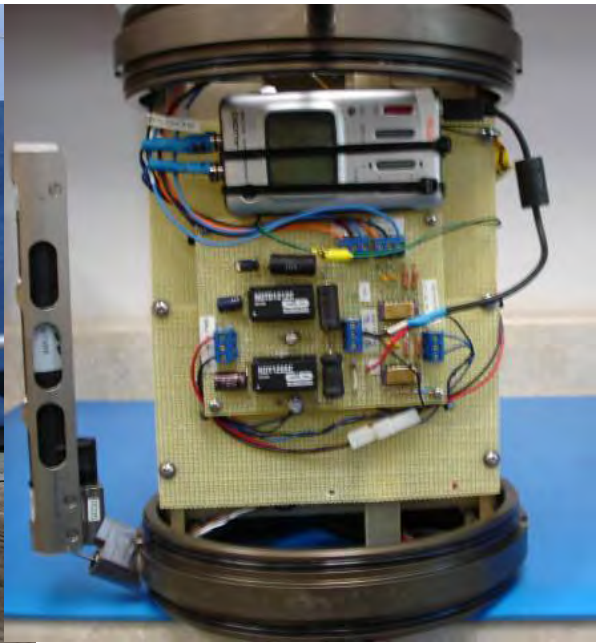
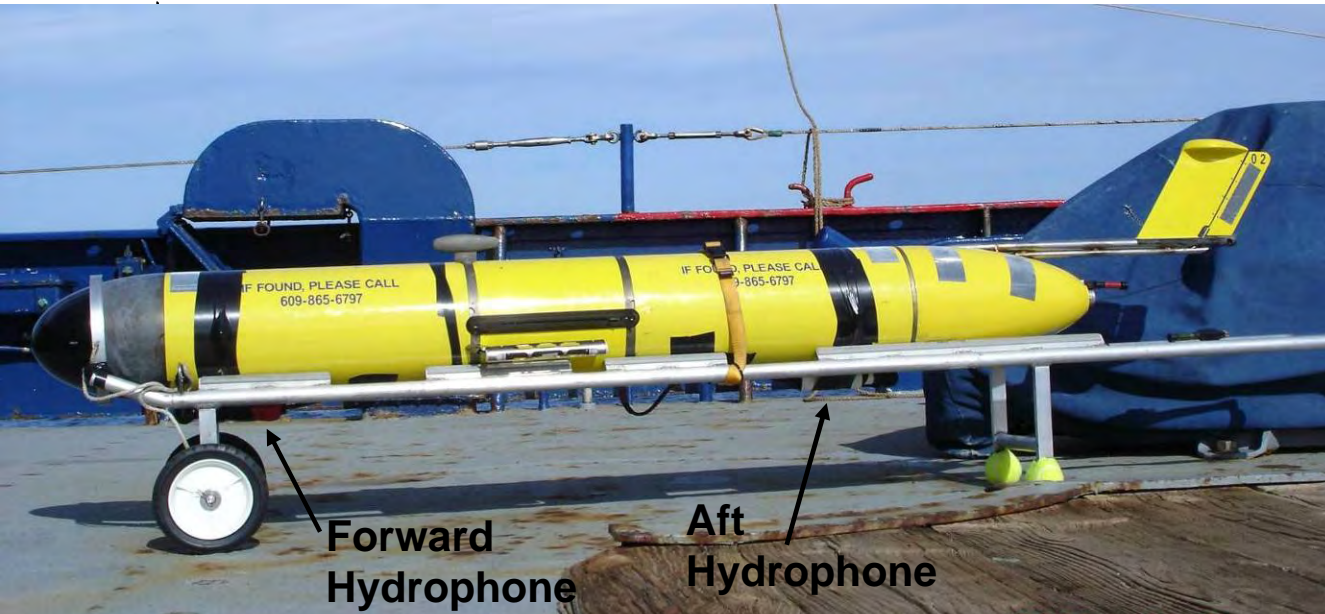
- Marine mammal consultants
- Field test design (where and when to test)
- Received signals analysis (LF and HF)
- Design of 3-EAR (Ecological Acoustic Recorder) system for glider
- Measuring near-field humpback songs during LF tests





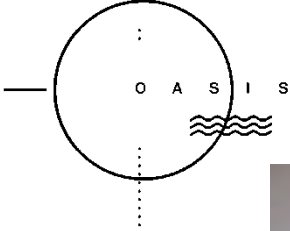


# OASIS HF Glider

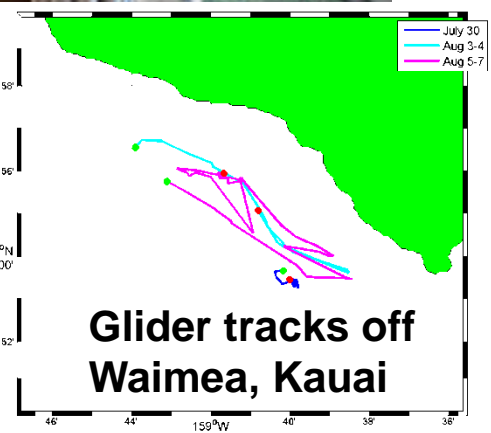
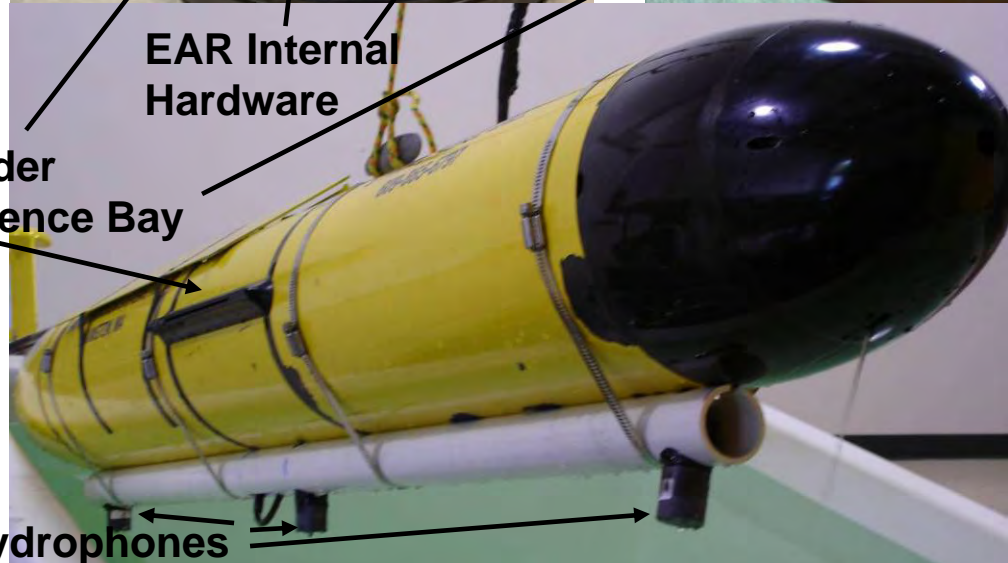
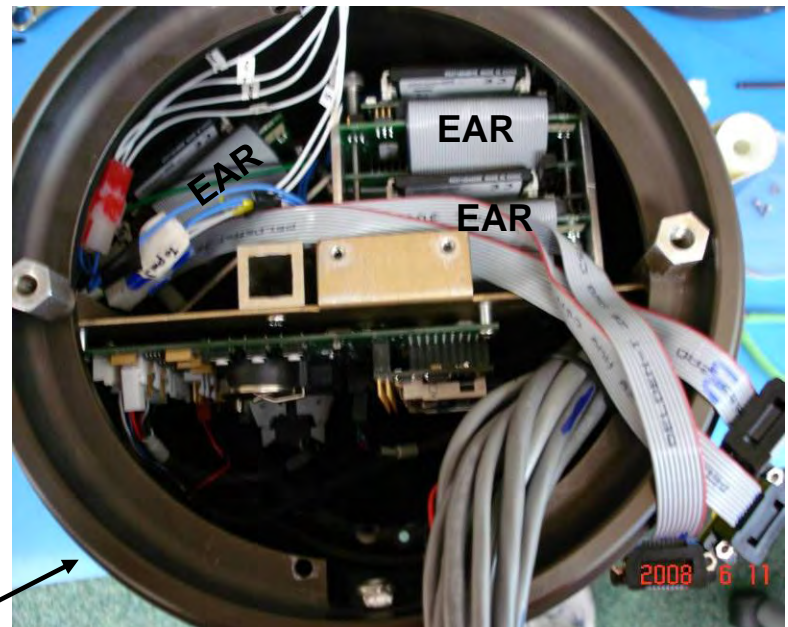


2/2/2009





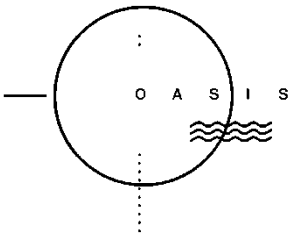
# HIMB HF Glider



**EAR Internal Hardware**

**Glider Science Bay**

**EAR Hydrophones**



# Summary

- Marine mammal monitoring is an important issue for the Navy, academia, commercial interests
- Most mammals vocalize with some regularity, allowing an opportunity for passive acoustic monitoring
- Gliders are a proven oceanographic sensor platform that can be outfitted with acoustic sensors
- Promise exists for species classification
- Successful tests of quiet, non-intrusive glider-based monitoring conducted
- Next phase of tests off Oahu in Feb/Mar 2009



# Questions?

